

HTPA16x16dR3L5.0/1.0F7.7

Datasheet for Thermopile Array Sensor with Lens Optic

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Changelog

| | |
|------------|---|
| 2024-03-15 | Initial release |
| 2024-07-12 | Pixel orientation is mirrored on the x-axis |
| 2024-12-18 | Updated graphic for optical orientation |
| 2025-01-31 | Updated order code, added order code chart w/ available options |
| 2025-04-28 | Updated operating conditions for IDD running, idle and standby |
| 2025-08-18 | Corrected graphic for pixel orientation |
| 2025-10-16 | Added max. measurable temperature |
| 2025-11-18 | Corrected accuracy specification |
| 2025-03-02 | Added calculation formula for CLK_Trim Register |

1 Cleaning and Handling of Sensors with Optical Elements

Cleaning of Filter with Isopropyl Alcohol or Acetone

This is the method most universally used for cleaning optical elements with or without coatings. Filters or lenses mounted in our sensors may be cleaned rubbing the surfaces lightly with a clean, soft, all-cotton cloth or cotton swab during immersion in solvent or simply moistened with the solvent. The parts are then immediately wiped dry with another clean, soft, all-cotton cloth or cotton swab.

Cleaning with Detergent and Water

A very mild, non-abrasive detergent (one which does not contain additives) and water may also be used for cleaning optical elements. In general, a detergent and water mixture is an excellent method for removing fingerprints and other smudges. The liquid detergent is first mixed with deionized water (proportions recommended by the manufacturer should be followed). The element is then washed, rinsed, and immediately wiped dry. Use a clean, soft cloth when cleaning and drying. If the part is allowed to dry in air, a permanent stain may result.

Please note:

- Do not use isopropyl alcohol or acetone or detergent if the elements will be mounted in an assembly with a finish which may be soluble by these solvents.
- Please avoid glass isolation being moistened by solvent.
- If the part is allowed to dry in air, a permanent stain may result.

Handling Advice

Sensors with optical elements deserve special consideration in their handling and care. Ordinarily, filters or lenses are cleaned and inspected prior to shipment. If proper care is exercised during handling cleaning should not be necessary prior to use.

- Wear gloves when handling a sensor or optical element. Lightweight nylon or cotton gloves, which are relatively lint-free are recommended.
- Avoid touching the surface of filters and lenses.
- Protect devices from static discharge and static fields.
- Thermopile sensors are electrostatic sensitive devices. Sensors should be handled over an electrostatic protected work area.
- Precautions should be taken to avoid reverse polarity of power supply for sensors with integrated signal processing. Reversed polarity of power supply results in a destroyed unit.
- Sensors should rest preferably in a partitioned container where the mounted filters or lenses will be not coming into contact with other material.
- During storage optical surfaces should be covered to avoid contamination from the surrounding environment.

- A covered container can eliminate damage during transportation and storage.
- Sensors or optical elements should be stored in a restricted access area to eliminate handling.
- Do not expose the sensors to aggressive detergents such as freon, trichlorethylen, etc.
- Avoid rotating the sensors when they are soldered into a PCB or something similar.
- Shortening of the pins is not suggested. This may cause cracks in the glass of the pins and result in a leakage.
- If this is necessary, a tool for this is recommended. Please contact Heimann Sensor for further information.

Soldering Recommendations

Attention: For all of our array sensors we give no guarantee on the calibration and its performance if the pins are shortened by the customer. Additionally, **we strongly recommend to not solder the sensor with its backplate directly to a PCB.** This will cause different thermal conductivity compared to air and the measurement results could get worse. **Use a minimum gap between PCB and backplate of 2 mm or more.** The glass of the pins to the back plate can get damage by applying high temperatures (during soldering), which will lead into a lower temperature reading what cannot be repaired afterwards.

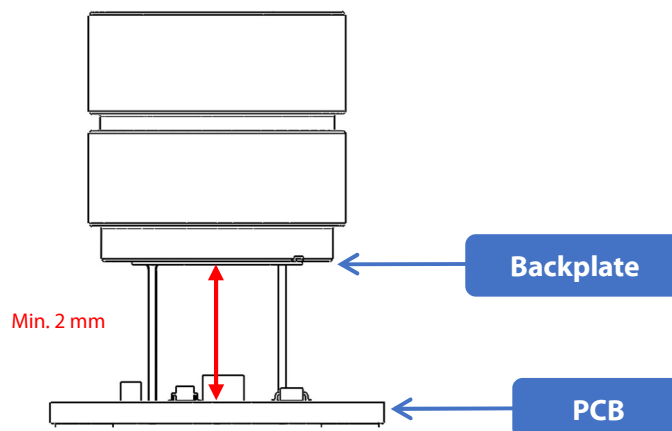


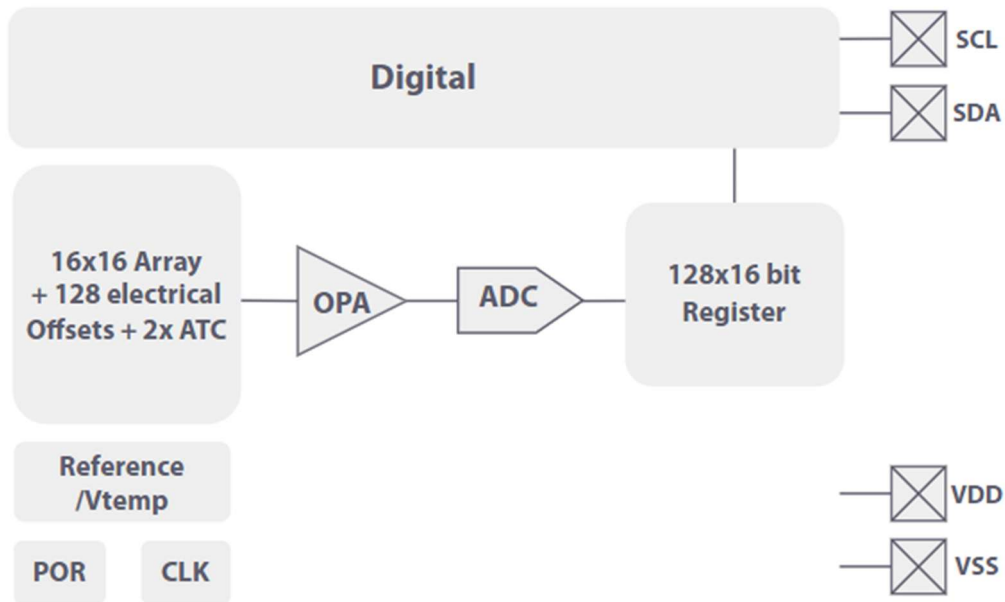
Figure 1: Soldering height

Manual Iron Soldering and Automatic Point-to-Point Iron Soldering

Manual Iron Soldering and Automatic Point-to-Point Iron Soldering methods are allowed for TO packages. It is recommended for through hole applications to shield the package body from soldering heat by PCB or similar.

The soldering iron temperature should be set as low as possible (maximum 350 °C) and should not exceed recommended soldering time (maximum 3 seconds). The minimum distance between the housing body and the liquid solder should be at least 1.5 mm for 350 °C. Reflow soldering is not recommended.

2 Principal Schematic for HTPA16x16d



3 Pin Assignment– Bottom View

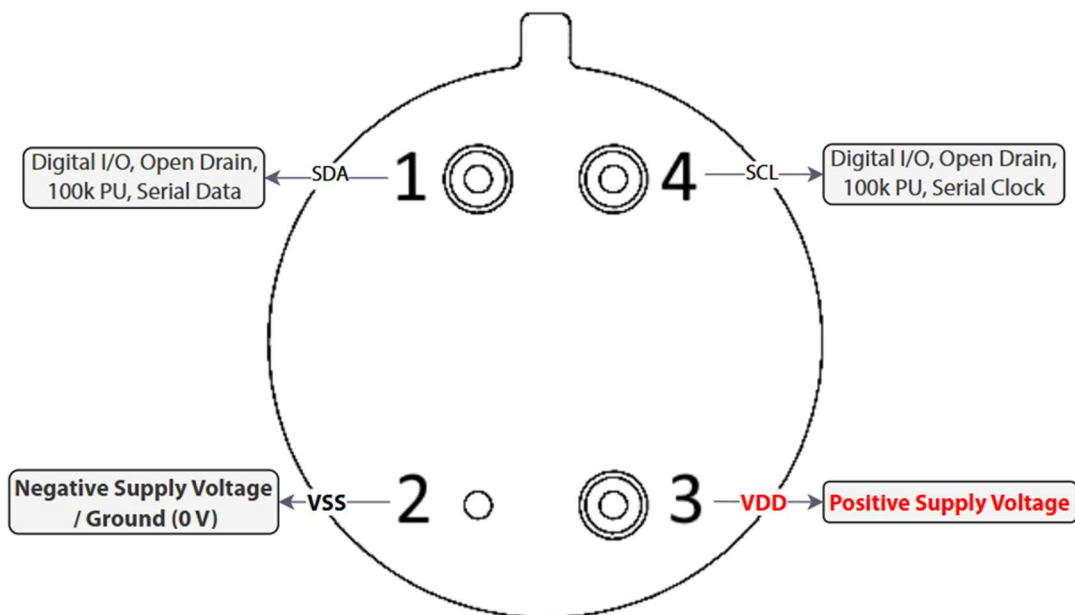
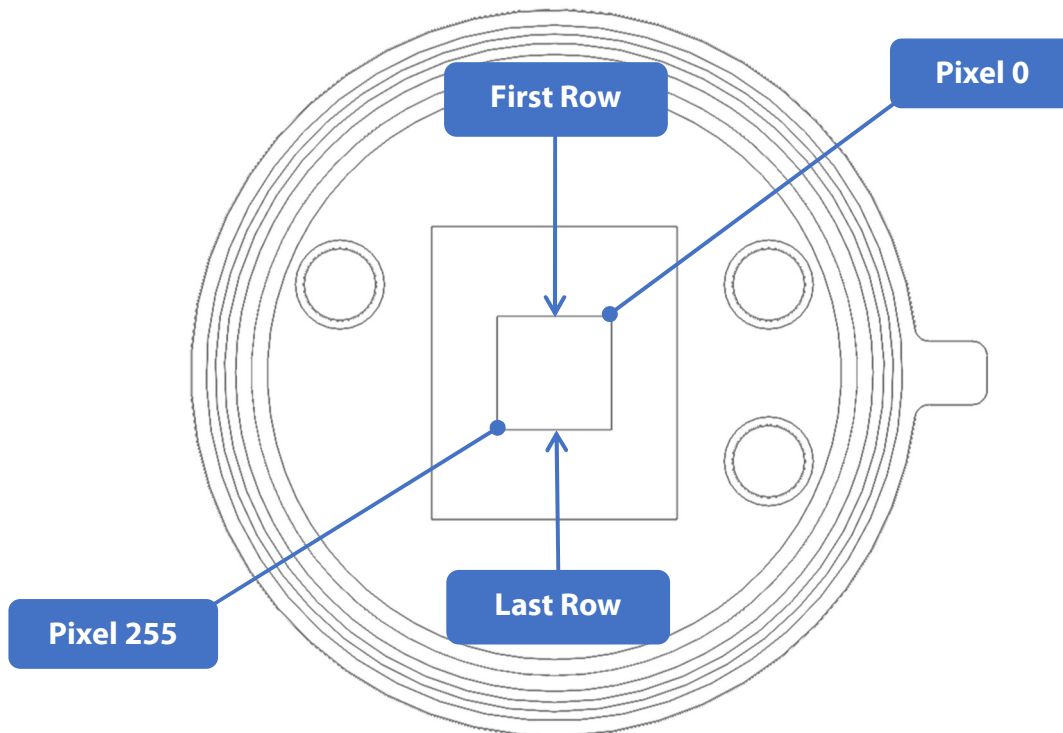
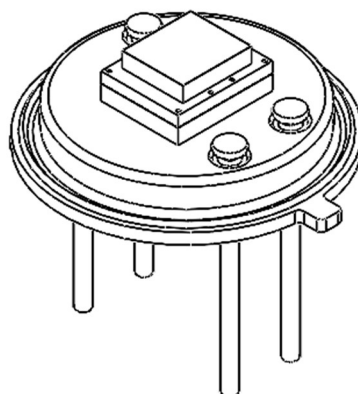


Figure 2: Pin-allocation

4 Optical Orientation



This illustration shows the pixel orientation after mirroring through the lens.



5 Order Code Example

| | | | | | | | |
|------------|----|----------|------|---|----|---|-------|
| HTPA32x32d | R2 | L5.0/0.8 | F7.7 | e | Hi | M | (UDP) |
| 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |

| | | Description |
|---|-------------------|--|
| 1 | Sensortype | TP Array with 32x32 Pixel For all available HTPA and module combinations contact our support |
| 2 | Revision | Silicon revision 2 |
| 3 | Optics | Focal length/F-Number Focal length: L5.0 = 5.0 mm F-Number: 0.8 |
| 4 | Filter | F: Filter characteristics Not declared: Broadband AR Coating |
| 5 | External Aperture | Not declared: without external aperture e: with external aperture |
| 6 | Sensitivity | UHi: increased sensitivity Hi: default sensitivity Not declared: lower sensitivity (greater measurement range) |
| 7 | Version | A: Application Set: comes with GUI, housing, power supply C: Calibrated sensor M: Modul: HTPA sensor soldered to PCB, calibrated stream |
| 8 | Interface | UDP: Ethernet connection, CAT5 PoE: Power over Ethernet, CAT5* i ² C: 4 Pin Connector* USB: Power and data via USB 2.0** * Interface option is only available for modules (HiM) ** Interface option is only available for Application Set (HiA) *** Interface option is only available for calibrated sensors (HiC) |

6 Application Note

A pull-up resistor of 4.7 k Ω for the I²C pins (SDA and SCL) is recommended. In addition, adding 100 nF and 47 μ F are improving the stability of the supply voltage.

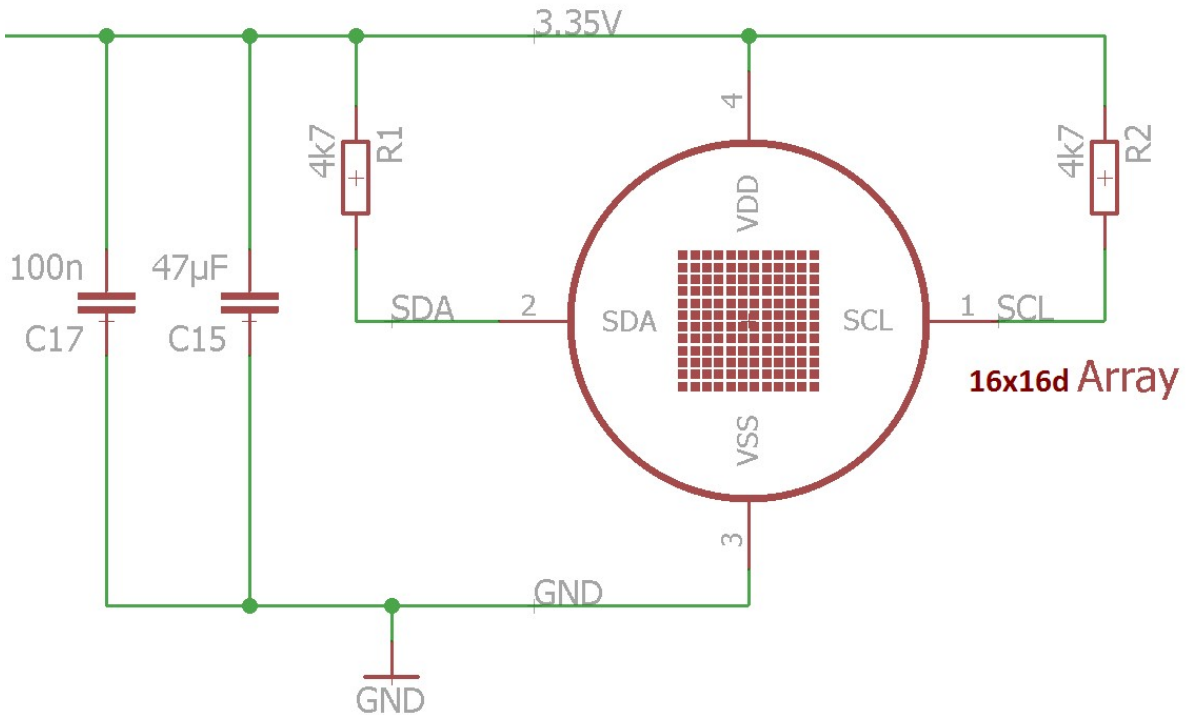


Figure 3: Recommended circuit for operation

The sensor can be powered directly via 3.35 V if the supply voltage is stable enough, this has to be measured before and tested with the sensor. It is important to not insert any inductor or otherwise the noise will increase.

7 Serial Order of Frame

The sensor is divided into two parts (top and bottom half), which are again separated into 2 blocks. The readout order is shown below for the different blocks.

| |
|------------------|
| Block 0 (top) |
| Block 1 (top) |
| Block 1 (bottom) |
| Block 0 (bottom) |

Figure 4: Division of blocks

Whenever a conversion is started the Block x of the top and bottom half are measured at the same time. Each block consists of 64 Pixel that are sampled fully parallel. The readout order on the bottom half is mirrored compared to the top half so that the central lines are always read last.

| | | | | | | | | | | | | | | | |
|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 |
| 16 | 17 | 18 | 19 | 20 | 21 | 22 | 23 | 24 | 25 | 26 | 27 | 28 | 29 | 30 | 31 |
| 32 | 33 | 34 | 35 | 36 | 37 | 38 | 39 | 40 | 41 | 42 | 43 | 44 | 45 | 46 | 47 |
| 48 | 49 | 50 | 51 | 52 | 53 | 54 | 55 | 56 | 57 | 58 | 59 | 60 | 61 | 62 | 63 |
| 64 | 65 | 66 | 67 | 68 | 69 | 70 | 71 | 72 | 73 | 74 | 75 | 76 | 77 | 78 | 79 |
| 80 | 81 | 82 | 83 | 84 | 85 | 86 | 87 | 88 | 89 | 90 | 91 | 92 | 93 | 94 | 95 |
| 96 | 97 | 98 | 99 | 100 | 101 | 102 | 103 | 104 | 105 | 106 | 107 | 108 | 109 | 110 | 111 |
| 112 | 113 | 114 | 115 | 116 | 117 | 118 | 119 | 120 | 121 | 122 | 123 | 124 | 125 | 126 | 127 |
| 128 | 129 | 130 | 131 | 132 | 133 | 134 | 135 | 136 | 137 | 138 | 139 | 140 | 141 | 142 | 143 |
| 144 | 145 | 146 | 147 | 148 | 149 | 150 | 151 | 152 | 153 | 154 | 155 | 156 | 157 | 158 | 159 |
| 160 | 161 | 162 | 163 | 164 | 165 | 166 | 167 | 168 | 169 | 170 | 171 | 172 | 173 | 174 | 175 |
| 176 | 177 | 178 | 179 | 180 | 181 | 182 | 183 | 184 | 185 | 186 | 187 | 188 | 189 | 190 | 191 |
| 192 | 193 | 194 | 195 | 196 | 197 | 198 | 199 | 200 | 201 | 202 | 203 | 204 | 205 | 206 | 207 |
| 208 | 209 | 210 | 211 | 212 | 213 | 214 | 215 | 216 | 217 | 218 | 219 | 220 | 221 | 222 | 223 |
| 224 | 225 | 226 | 227 | 228 | 229 | 230 | 231 | 232 | 233 | 234 | 235 | 236 | 237 | 238 | 239 |
| 240 | 241 | 242 | 243 | 244 | 245 | 246 | 247 | 248 | 249 | 250 | 251 | 252 | 253 | 254 | 255 |

readout order top

readout order bottom

Figure 5: 16x16d readout order for active pixel

The electrical offsets are sampled in parallel for the top and bottom half. The matching rows for the corresponding electrical offsets and active Pixel are marked with the same color. The conversion of the electrical offsets is started by sending the command for the BLIND bit during the start command.

| | | | | | | | | | | | | | | | |
|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 |
| 16 | 17 | 18 | 19 | 20 | 21 | 22 | 23 | 24 | 25 | 26 | 27 | 28 | 29 | 30 | 31 |
| 32 | 33 | 34 | 35 | 36 | 37 | 38 | 39 | 40 | 41 | 42 | 43 | 44 | 45 | 46 | 47 |
| 48 | 49 | 50 | 51 | 52 | 53 | 54 | 55 | 56 | 57 | 58 | 59 | 60 | 61 | 62 | 63 |
| 64 | 65 | 66 | 67 | 68 | 69 | 70 | 71 | 72 | 73 | 74 | 75 | 76 | 77 | 78 | 79 |
| 80 | 81 | 82 | 83 | 84 | 85 | 86 | 87 | 88 | 89 | 90 | 91 | 92 | 93 | 94 | 95 |
| 96 | 97 | 98 | 99 | 100 | 101 | 102 | 103 | 104 | 105 | 106 | 107 | 108 | 109 | 110 | 111 |
| 112 | 113 | 114 | 115 | 116 | 117 | 118 | 119 | 120 | 121 | 122 | 123 | 124 | 125 | 126 | 127 |

readout order top

readout order bottom

Figure 6: 16x16d readout order for electrical offset

8 Characteristics

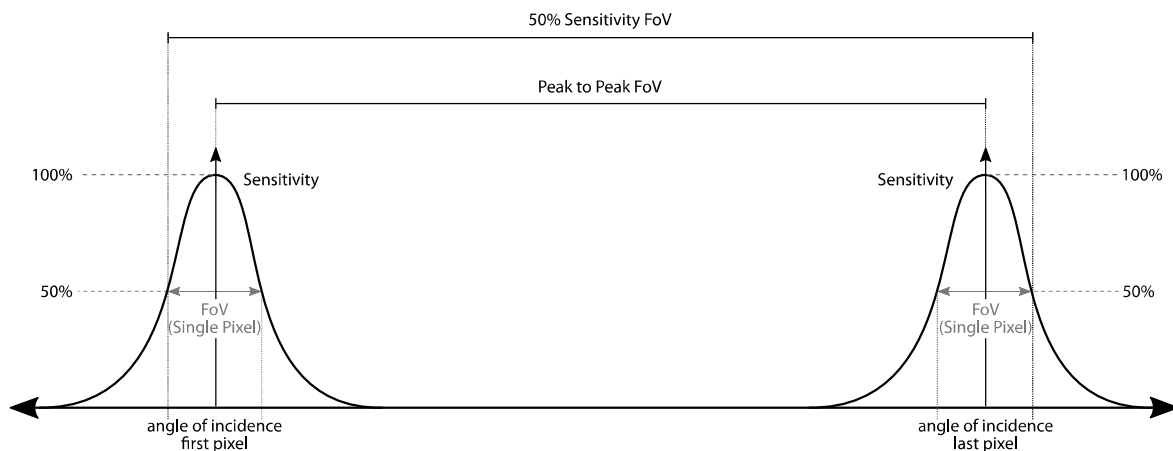
8.1 Common Specifications

| | |
|------------------------------|---|
| Technology: | n-poly/p-poly Si |
| Element Resistance: | approx. 300 kOhms |
| Thermal pixel time constant: | <4 ms |
| Digital Interface: | I ² C |
| EEPROM size: | 1024 x 16 Bit |
| Pitch: | 90 µm |
| Absorber size: | 44 µm |
| Max. Framerate: | 120 Hz |
| Max. measurable temperature: | 300°C with default settings 600°C with RefCal0 |

(complete frame with maximum I²C and sensor clock speed and reduced ADC resolution)
256 sensitive elements

8.2 Optical Characteristics

| | |
|----------------|--|
| Focal length: | 5.0 mm ("L" equals the focal length of the lens) |
| F-Number: | 0.8 |
| Field of view: | 16 x 16 deg. (50 % sensitivity FoV) |



| | |
|---------------|---|
| Lens coating: | LWP-Coating 5.0 Cut On (Tr. 5 %): 5.0 µm |
|---------------|---|

| | |
|-----------|--|
| Accuracy: | ±3 % or ±3 K (whichever is larger) in the working ambient temperature range of 5° to 50 °C and object temperatures ≤ to 300 °C |
|-----------|--|

9 Electric Specifications

Table 1: Absolute Maximum Ratings

| Parameter | Symbol | Condition | MIN. | TYP. | MAX. | Unit |
|-----------------------------------|--------|-----------|------|------|---------|--------|
| Supply Voltage | VDD | | -0.3 | | 3.6 | V |
| Voltage at all inputs and outputs | VIO | | -0.3 | | VDD+0.3 | V |
| Storage Temperature | TSTG | | -40 | | 85 | Deg. C |

Table 2: Operating Conditions

| Parameter | Symbol | Condition | MIN. | TYP. | MAX. | Unit |
|---|------------------|------------------|------|------|------|--------|
| Supply Voltage | V _{DD} | | 3.3 | 3.35 | 3.6 | V |
| Supply Current (sensor running) | I _{DD} | | 3.7 | 4.0 | 4.3 | mA |
| Supply Current (sensor in idle state) | I _{SBY} | | 3.5 | 3.7 | 3.9 | mA |
| Standby Current (sensor in sleep state) | I _{SBY} | | 8.4 | 8.6 | 8.8 | μA |
| Operation Temperature | T _A | | -20 | | 65 | Deg. C |
| ESD-Protection | | Human body model | 2 | | | kV |
| | | 100pF + 1k50hm | | | | |

Table 3: Electrical Characteristics

| Parameter | Symbol | Condition | MIN. | TYP. | MAX. | Unit |
|-----------------------------------|-------------------|-----------|---------------------|------|---------------------|--------|
| Digital Input | | | | | | |
| Internal Clock frequency | F _{CLK} | | 1 | 5 | 13 | MHz |
| Internal I ² C Pull up | R _{PU} | | 1 | 100 | 100 | kOhm |
| BIAS current | I _{BIAS} | | 1 | 3 | 13 | μA |
| BPA current | I _{BPA} | | 0.2 | 1.5 | 4.0 | μA |
| Input voltage high | V _{IH} | | 0.7xV _{DD} | | | V |
| Input voltage low | V _{IL} | | | | 0.3xV _{DD} | V |
| PTAT | | | | | | |
| Temperature range | | | TBD | | TBD | Deg. C |
| PTAT gradient | | | | TBD | | K/V |

Table 4: Preamplifier / ADC

| Parameter | Symbol | Condition | MIN. | TYP. | MAX. | Unit |
|-------------------------|--------------------|-----------|------|------|------|----------------------|
| Chopper frequency | F _{CHP} | | | 20 | | kHz |
| Preamplifier Noise | N _{PA} | at 20 kHz | | 72 | | nV/Hz ^{1/2} |
| Frame rate (Full Array) | FR1 | | | 18 | | Hz |
| Frame rate (Half Array) | FR4 | | | 36 | | Hz |
| ADC pos. Reference | V _{REFP} | | | 1.6 | | V |
| ADC pos. Reference | V _{REFP} | | | 0.9 | | V |
| ADC resolution | ADC _{LSB} | at 16-Bit | | 21 | | μV |

10 I²C Timings HTPA16x16d

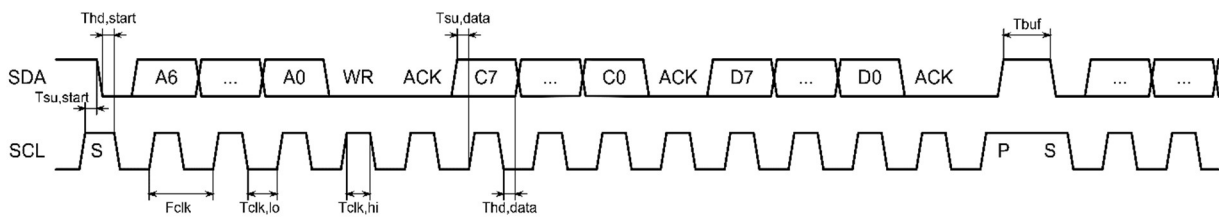


Figure 7: I²C Timings of HTPA16x16d

Table 5: I²C Timings

| Parameter | Symbol | Condition | MIN. | TYP. | MAX. | Unit |
|-------------------------------------|-----------------------|-----------|------|------|------|------|
| I ² C clock frequency | F _{CLK} | | | 400 | 1000 | kHz |
| low pulse duration | T _{CLK,lo} | | 0.50 | | | μs |
| high pulse duration | T _{CLK,hi} | | 0.26 | | | μs |
| data set up time | T _{SU,data} | | 0.05 | | | μs |
| data hold time | T _{hd,data} | | 0.00 | | | μs |
| start setup time | T _{SU,start} | | 0.26 | | | μs |
| start hold time | T _{hd,start} | | 0.26 | | | μs |
| stop setup time | T _{SU,stop} | | 0.26 | | | μs |
| stop hold time | T _{hd,stop} | | 0.26 | | | μs |
| time between STOP / START | T _{buf} | | 0.50 | | | μs |
| Time startup (after Power-on Reset) | T _{startup} | | | | 100 | μs |
| Time wakeup (after sending WAKEUP) | T _{wakeup} | | | | 80 | μs |

11 I²C Communication

The chip uses the 7-bit I²C address 0x1A for configuration and sensor data and the address 0x1B to access the internal EEPROM followed by 1-bit of read/write command. The address byte is followed by an 8-bit command.

11.1 Write Command

In case of a write access to an internal register the command is followed by the data byte. The chip acknowledges each byte with a low active ACK bit.

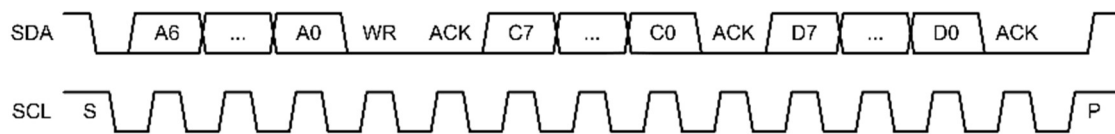


Figure 8: Write Command

11.2 Read Command

To read data from the chip first the address and command must be sent. After the last ACK a new start-bit (repeated start) and the address with a set read-flag initiates the read sequence. There can be bytes read as many as required. The last byte must be denoted by a not-acknowledge. The shown example below can be used e.g. to get the status register.

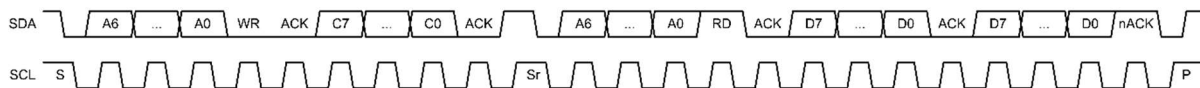


Figure 9: Read Command

11.3 Sensor Commands

The sensor has several registers that can be written and read, they are listed below.

Table 6: Configuration Register (write only)

| Addr / CMD | 0x1A (7-bit!)/ 0x01 | | | | | | | |
|-------------------|---------------------|---|---|---|-------|----------|-------|--------|
| Config Reg | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Name | RFU | | | | START | VDD_MEAS | BLIND | WAKEUP |
| Default | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

The WAKEUP bit is used to switch on / off the chip and must be set prior all other operations. After the START bit is set the chip starts a conversion of the array or blind elements and enters the idle state (not sleep!), when finished.

If the BLIND bit is set the electrical offsets are sampled instead of the active pixel.

If VDD_MEAS bit is set the VDD voltage is measured instead of the PTAT value.

RFU means reserved for future use and can be subject to change.

Table 7: Status Register (read only)

| Addr / CMD | 0x1A (7-bit!)/ 0x02 | | | | | | | |
|------------|---------------------|---|---|---|-------|----------|---|-----|
| Status Reg | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Name | RFU | | | | Block | VDD_MEAS | | EOC |
| Default | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

If the EOC flag is set a previous started conversion has been finished.

Trim Register 1 (write only)

| Addr / CMD | 0x1A (7-bit!)/ 0x03 | | | | | | | |
|------------|---------------------|---|---|---|-----------|---|---|---|
| Trim Reg 1 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Name | RFU | | | | MBIT TRIM | | | |

REF_CAL: selectable amplification

MBIT_TRIM: m = 4 to 12 ⇒ (m+4) bit as ADC resolution

Trim Register 2 (write only)

| Addr / CMD | 0x1A (7-bit!)/ 0x04 | | | | | | | |
|------------|---------------------|---|---|---|---------------|---|---|---|
| Trim Reg 2 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Name | RFU | | | | BIAS TRIM TOP | | | |

BIAS_TRIM_TOP: 0 to 31 ⇒ 1 µA to 13 µA

This setting is used to adjust the BIAS current of the ADC. A faster clock frequency requires a higher BIAS current setting.

Trim Register 3 (write only)

| Addr / CMD | 0x1A (7-bit!)/ 0x05 | | | | | | | |
|------------|---------------------|---|---|---|---------------|---|---|---|
| Trim Reg 3 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Name | RFU | | | | BIAS TRIM BOT | | | |

BIAS_TRIM_BOT: 0 to 31 ⇒ 1 µA to 13 µA

This setting is used to adjust the BIAS current of the ADC. A faster clock frequency requires a higher BIAS current setting.

Trim Register 4 (write only)

| Addr / CMD | 0x1A (7-bit!)/ 0x06 | | | | | | | |
|------------|---------------------|---|---|---|----------|---|---|---|
| Trim Reg 4 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Name | RFU | | | | CLK TRIM | | | |

CLK_TRIM ranges from 0 to 63 and corresponds the clock frequency F_{CLK} which can be determined via the following formula:

$$F_{CLK} = \left(F_{CLK,min} + \frac{F_{CLK,max} - F_{CLK,min}}{63} \cdot CLK_TRIM \right) \text{ MHz}$$

with

$$F_{CLK,min} = 1 \text{ MHz}$$

$$F_{CLK,max} = 13 \text{ MHz}$$

The measure time depends on the clock frequency settings. One quarter frame takes about:

$$t_{fr4} = \frac{32 \cdot (2^{MBIT} + 4)}{F_{CLK}} \approx 27ms@5MHz$$

MBIT is equal to MBIT TRIM In Trim Register 1.

Trim Register 5 (write only)

| Addr / CMD | 0x1A (7-bit!)/ 0x07 | | | | | | | |
|-------------------|---------------------|---|---|---------------|---|---|---|---|
| Trim Reg 5 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Name | RFU | | | BIAS TRIM TOP | | | | |

BPA_TRIM_TOP: 0 to 31 ⇒ 0.2 µA to 4.0 µA

This setting is used to adjust the common mode voltage of the preamplifier.

Trim Register 6 (write only)

| Addr / CMD | 0x1A (7-bit!)/ 0x08 | | | | | | | |
|-------------------|---------------------|---|---|---------------|---|---|---|---|
| Trim Reg 6 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Name | RFU | | | BIAS TRIM BOT | | | | |

BPA_TRIM_BOT: 0 to 31 ⇒ 0.2 µA to 4.0 µA

This setting is used to adjust the common mode voltage of the preamplifier.

Trim Register 7 (write only)

| Addr / CMD | 0x1A (7-bit!)/ 0x09 | | | | | | | |
|-------------------|---------------------|---|---|---|-------------|---|---|---|
| Trim Reg 7 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Name | PU SDA TRIM | | | | PU SCL TRIM | | | |

PU_SDA_TRIM: select internal pull up resistor on SDA (Default: 100 kOhm)

PU_SCL_TRIM: select internal pull up resistor on SCL (Default: 100 kOhm)

“1000” = 100 kOhm; “0100” = 50 kOhm; “0010” = 10 kOhm; “0001” = 1 kOhm

Table 8: Read Data 1 Command (Top Half of Array)

| Addr / CMD | 0x1A (7 Bit!)/ 0x0A | | | | | | | |
|------------------------------|-------------------------------------|---|---|---|---|---|---|---|
| Read Data | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 1. Byte / 2. Byte | PTAT 1 MSB / LSB or VDD 1 MSB / LSB | | | | | | | |
| 3. Byte / 4. Byte | ATC 1 MSB / LSB | | | | | | | |
| 5. Byte / 6. Byte | Pixel (0+BLOCK*64) MSB / LSB | | | | | | | |
| 7. Byte / 8. Byte | Pixel (1+BLOCK*64) MSB / LSB | | | | | | | |
| ... | ... | | | | | | | |
| 129. Byte / 130. Byte | Pixel (63+BLOCK*64) MSB / LSB | | | | | | | |

Table 9: Read Data 2 Command (Bottom Half of Array)

| Addr / CMD | 0x1A (7 Bit!) / 0x0B | | | | | | | |
|-----------------------|-------------------------------------|---|---|---|---|---|---|---|
| Read Data | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 1. Byte / 2. Byte | PTAT 2 MSB / LSB or VDD 2 MSB / LSB | | | | | | | |
| 3. Byte / 4. Byte | ATC 2 MSB / LSB | | | | | | | |
| 5. Byte / 6. Byte | Pixel (240-BLOCK*64) MSB / LSB | | | | | | | |
| 7. Byte / 8. Byte | Pixel (241-BLOCK*64) MSB / LSB | | | | | | | |
| ... | | | | | | | | |
| 35. Byte / 36. Byte | Pixel (255-BLOCK*64) MSB / LSB | | | | | | | |
| 37. Byte / 38. Byte | Pixel (224-BLOCK*64) MSB / LSB | | | | | | | |
| 39. Byte / 40. Byte | Pixel (225-BLOCK*64) MSB / LSB | | | | | | | |
| ... | | | | | | | | |
| 67. Byte / 68. Byte | Pixel (239-BLOCK*64) MSB / LSB | | | | | | | |
| 69. Byte / 70. Byte | Pixel (192-BLOCK*64) MSB / LSB | | | | | | | |
| ... | | | | | | | | |
| 131. Byte / 132. Byte | Pixel (207-BLOCK*64) MSB / LSB | | | | | | | |

The complete sensor data must be read at once. If the communication fails somewhere in between, all successive data will be corrupted. The readout can be stopped anywhere by pausing the clock. A new initialized readout proceeds at this stopped byte by continuing the clock, but the index is reset when a new conversion has been started.

If the bit for the electrical offsets (Bit 1 in Config 0x01) is set the electrical offsets are sampled and can be read similar to the active pixel:

Read Data Electrical Offsets (Top Half of Array)

| Addr / CMD | 0x1A (7-bit!)/ 0x0A | | | | | | | |
|-----------------------|-------------------------------------|---|---|---|---|---|---|---|
| Read Data | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 1. Byte / 2. Byte | PTAT 1 MSB / LSB or VDD 1 MSB / LSB | | | | | | | |
| 3. Byte / 4. Byte | ATC 1 MSB / LSB | | | | | | | |
| 5. Byte / 6. Byte | electrical offset (0) MSB / LSB | | | | | | | |
| 7. Byte / 8. Byte | electrical offset (1) MSB / LSB | | | | | | | |
| ... | ... | | | | | | | |
| 131. Byte / 132. Byte | electrical offset (63) MSB / LSB | | | | | | | |

Read Data Electrical Offsets (Bottom Half of Array)

| Addr / CMD | 0x1A (7 Bit!) / 0x0B | | | | | | | |
|-------------------|-------------------------------------|---|---|---|---|---|---|---|
| Read Data | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| 1. Byte / 2. Byte | PTAT 2 MSB / LSB or VDD 2 MSB / LSB | | | | | | | |
| 3. Byte / 4. Byte | ATC 2 MSB / LSB | | | | | | | |
| 5. Byte / 6. Byte | electrical offset (112) MSB / LSB | | | | | | | |
| 7. Byte / 8. Byte | electrical offset (113) MSB / LSB | | | | | | | |

| | |
|------------------------------|-----------------------------------|
| ... | ... |
| 35. Byte / 36. Byte | electrical offset (127) MSB / LSB |
| 37. Byte / 38. Byte | electrical offset (96) MSB / LSB |
| ... | ... |
| 131. Byte / 132. Byte | electrical offset (79) MSB / LSB |

The complete sensor data must be read at once. If the communication fails somewhere in between, all successive data will be corrupted. The readout can be stopped anywhere by pausing the clock. A new initialized readout proceeds at this stopped byte by continuing the clock, but the index is reset when a new conversion has been started.

11.4 EEPROM Commands

To read/write data from/to the internal EEPROM the I²C address 0x1B is used.

EEPROM Commands

| Name | CMD | Read / Write | Comment |
|---------------------|------|--------------|---|
| Standby | 0x00 | W | |
| Active | 0x01 | W | releases all signals to default state wait for 15μs when wake up from standby |
| Normal Erase | 0x02 | W | program pulse width 5ms |
| Normal Write | 0x03 | W | program pulse width 5ms |
| Block Erase | 0x04 | W | program pulse width 5ms |
| Block Write | 0x05 | W | program pulse width 5ms |
| Normal Read | 0x06 | W | program pulse width 5ms |
| Set Address | 0x09 | W | program pulse width 5ms |
| Set Data | 0x0A | W | 16 bit data, MSB first |
| Get Data | 0x0B | R | 16 bit data, MSB first |

Note:

The EEPROM must be activated (wake up from standby) prior being used. The active command also initializes the EEPROM to its default state.

Note:

Each word must be erased before it can be written, a write command stores only a "1" to the EEPROM cell. Note: The commands "SET_DATA" / "GET_DATA" will increment the address pointer, except for the first execution after "SET_ADDR".

11.5 I²C Example Sequences – EEPROM Wakeup / Standby

| | ADDR | W/R | EEPROM_ACTIVE | |
|---|------|-----|---------------|---|
| S | 0x1B | 0 | 0x01 | P |

| | ADDR | W/R | EEPROM_STANDBY | |
|---|------|-----|----------------|---|
| S | 0x1B | 0 | 0x00 | P |

11.6 I²C Example Sequences – EEPROM Block Erase / Block Write

| | ADDR | W/R | EEPROM_ACTIVE | |
|---|------|-----|---------------|---|
| S | 0x1B | 0 | 0x01 | P |

wait 1 ms

| | ADDR | W/R | BLOCK_ERASE | |
|---|------|-----|-------------|---|
| S | 0x1B | 0 | 0x04 | P |

wait 5 ms

| | ADDR | W/R | SET_DATA | DATA_MSB | DATA_LSB | |
|---|------|-----|----------|----------|----------|---|
| S | 0x1B | 0 | 0x0A | DATA | DATA | P |

| | ADDR | W/R | BLOCK_WRITE | |
|---|------|-----|-------------|---|
| S | 0x1B | 0 | 0x05 | P |

wait 5 ms

| | ADDR | W/R | STANDBY | |
|---|------|-----|---------|---|
| S | 0x1B | 0 | 0x00 | P |

11.7 I²C Example Sequences – EEPROM Sequential Erase / Write

| | ADDR | W/R | EEPROM_ACTIVE | |
|---|------|-----|---------------|---|
| S | 0x1B | 0 | 0x01 | P |

wait 1 ms

| | ADDR | W/R | SET_ADDR | EEP_ADDR | |
|---|------|-----|----------|----------|---|
| S | 0x1B | 0 | 0x09 | ADDR | P |

| | ADDR | W/R | NORMAL_ERASE | |
|---|------|-----|--------------|---|
| S | 0x1B | 0 | 0x02 | P |

wait 5 ms

| | ADDR | W/R | SET_DATA | DATA_MSB | DATA_LSB | |
|---|------|-----|----------|----------|----------|---|
| S | 0x1B | 0 | 0x0A | DATA | DATA | P |

| | ADDR | W/R | NORMAL_WRITE | |
|---|------|-----|--------------|---|
| S | 0x1B | 0 | 0x03 | P |

wait 5 ms

| | ADDR | W/R | SET_ADDR | EEP_ADDR | |
|---|------|-----|----------|----------|---|
| S | 0x1B | 0 | 0x09 | ADDR | P |

| | ADDR | W/R | NORMAL_ERASE | |
|---|------|-----|--------------|---|
| S | 0x1B | 0 | 0x02 | P |

wait 5 ms

| | ADDR | W/R | SET_DATA | DATA_MSB | DATA_LSB | |
|---|------|-----|----------|----------|----------|---|
| S | 0x1B | 0 | 0x0A | DATA | DATA | P |

| | ADDR | W/R | NORMAL_WRITE | |
|---|------|-----|--------------|---|
| S | 0x1B | 0 | 0x03 | P |

wait 5 ms

| | ADDR | W/R | SET_ADDR | EEP_ADDR | |
|---|------|-----|----------|----------|---|
| S | 0x1B | 0 | 0x09 | ADDR | P |

| | ADDR | W/R | NORMAL_ERASE | |
|---|------|-----|--------------|---|
| S | 0x1B | 0 | 0x02 | P |

wait 5 ms

| | ADDR | W/R | SET_DATA | DATA_MSB | DATA_LSB | |
|---|------|-----|----------|----------|----------|---|
| S | 0x1B | 0 | 0x0A | DATA | DATA | P |

| | ADDR | W/R | NORMAL_WRITE | |
|---|------|-----|--------------|---|
| S | 0x1B | 0 | 0x03 | P |

wait 5 ms

| | ADDR | W/R | SET_ADDR | EEP_ADDR | |
|---|------|-----|----------|----------|---|
| S | 0x1B | 0 | 0x09 | ADDR | P |

| | ADDR | W/R | NORMAL_ERASE | |
|---|------|-----|--------------|---|
| S | 0x1B | 0 | 0x02 | P |

wait 5 ms

| | ADDR | W/R | STANDBY | |
|---|------|-----|---------|---|
| S | 0x1B | 0 | 0x00 | P |

11.8 I²C Example Sequence – EEPROM Continuous Erase

| | ADDR | W/R | EEPROM_ACTIVE | |
|---|------|-----|---------------|---|
| S | 0x1B | 0 | 0x01 | P |

wait 1 ms

| | ADDR | W/R | SET_ADDR | EEP_ADDR | |
|---|------|-----|----------|----------|---|
| S | 0x1B | 0 | 0x09 | ADDR | P |

| | ADDR | W/R | NORMAL_ERASE | |
|---|------|-----|--------------|---|
| S | 0x1B | 0 | 0x02 | P |

wait 5 ms

| | ADDR | W/R | SET_ADDR | EEP_ADDR | |
|---|------|-----|----------|----------|---|
| S | 0x1B | 0 | 0x09 | ADDR | P |

| | ADDR | W/R | NORMAL_ERASE | |
|---|------|-----|--------------|---|
| S | 0x1B | 0 | 0x02 | P |

wait 5 ms

| | ADDR | W/R | STANDBY | |
|---|------|-----|---------|---|
| S | 0x1B | 0 | 0x00 | P |

11.9 I²C Example Sequence – EEPROM Continuous Write

| | ADDR | W/R | EEPROM_ACTIVE | |
|---|------|-----|---------------|---|
| S | 0x1B | 0 | 0x01 | P |

wait 1 ms

| | ADDR | W/R | SET_ADDR | EEP_ADDR | |
|---|------|-----|----------|----------|---|
| S | 0x1B | 0 | 0x09 | ADDR | P |

| | ADDR | W/R | SET_DATA | DATA_MSB | DATA_LSB | |
|---|------|-----|----------|----------|----------|---|
| S | 0x1B | 0 | 0x0A | DATA | DATA | P |

| | ADDR | W/R | NORMAL_WRITE | |
|---|------|-----|--------------|---|
| S | 0x1B | 0 | 0x03 | P |

wait 5 ms

| | ADDR | W/R | SET_DATA | DATA_MSB | DATA_LSB | |
|---|------|-----|----------|----------|----------|---|
| S | 0x1B | 0 | 0x0A | DATA | DATA | P |

| | ADDR | W/R | NORMAL_WRITE | |
|---|------|-----|--------------|---|
| S | 0x1B | 0 | 0x03 | P |

wait 5 ms

| | ADDR | W/R | STANDBY | |
|---|------|-----|---------|---|
| S | 0x1B | 0 | 0x00 | P |

11.10 I²C Example Sequence – EEPROM Sequential Read

| | ADDR | W/R | EEPROM_ACTIVE | |
|---|------|-----|---------------|---|
| S | 0x1B | 0 | 0x01 | P |

wait 1 ms

| | ADDR | W/R | SET_ADDR | EEP_ADDR | |
|---|------|-----|----------|----------|---|
| S | 0x1B | 0 | 0x09 | ADDR | P |

| | ADDR | W/R | NORMAL_READ | |
|---|------|-----|-------------|---|
| S | 0x1B | 0 | 0x06 | P |

| | ADDR | W/R | GET_DATA | | ADDR | W/R | DATA_MSB | DATA_LSB | |
|---|------|-----|----------|----|------|-----|----------|----------|---|
| S | 0x1B | 0 | 0x0B | Sr | 0x1B | 1 | ?? | ?? | P |

| | ADDR | W/R | SET_ADDR | EEP_ADDR | |
|---|------|-----|----------|----------|---|
| S | 0x1B | 0 | 0x09 | ADDR | P |

| | ADDR | W/R | NORMAL_READ | |
|---|------|-----|-------------|---|
| S | 0x1B | 0 | 0x06 | P |

| | ADDR | W/R | GET_DATA | | ADDR | W/R | DATA_MSB | DATA_LSB | |
|---|------|-----|----------|----|------|-----|----------|----------|---|
| S | 0x1B | 0 | 0x0B | Sr | 0x1B | 1 | ?? | ?? | P |

| | ADDR | W/R | STANDBY | |
|---|------|-----|---------|---|
| S | 0x1B | 0 | 0x00 | P |

11.11 I²C Example Sequence – EEPROM Continuous Read

| | ADDR | W/R | EEPROM_ACTIVE | |
|---|------|-----|---------------|---|
| S | 0x1B | 0 | 0x01 | P |

wait 1 ms

| | ADDR | W/R | SET_ADDR | EEP_ADDR | |
|---|------|-----|----------|----------|---|
| S | 0x1B | 0 | 0x09 | ADDR | P |

| | ADDR | W/R | NORMAL_READ | |
|---|------|-----|-------------|---|
| S | 0x1B | 0 | 0x06 | P |

| | ADDR | W/R | GET_DATA | | ADDR | W/R | DATA_MSB | DATA_LSB | |
|---|------|-----|----------|----|------|-----|----------|----------|---|
| S | 0x1B | 0 | 0x0B | Sr | 0x1B | 1 | ?? | ?? | P |

| | ADDR | W/R | GET_DATA | | ADDR | W/R | DATA_MSB | DATA_LSB | |
|---|------|-----|----------|----|------|-----|----------|----------|---|
| S | 0x1B | 0 | 0x0B | Sr | 0x1B | 1 | ?? | ?? | P |

| | ADDR | W/R | GET_DATA | | ADDR | W/R | DATA_MSB | DATA_LSB | |
|---|------|-----|----------|----|------|-----|----------|----------|---|
| S | 0x1B | 0 | 0x0B | Sr | 0x1B | 1 | ?? | ?? | P |

| | ADDR | W/R | GET_DATA | | ADDR | W/R | DATA_MSB | DATA_LSB | |
|---|------|-----|----------|----|------|-----|----------|----------|---|
| S | 0x1B | 0 | 0x0B | Sr | 0x1B | 1 | ?? | ?? | P |

| | ADDR | W/R | STANDBY | |
|---|------|-----|---------|---|
| S | 0x1B | 0 | 0x00 | P |

11.12 I²C Example Sequence – Init and Read Thermopile Array

| | ADDR | R/W | CONFIG_REG | WAKEUP | |
|---|------|-----|------------|--------|---|
| S | 0x1A | 0 | 0x01 | 0x01 | P |

| | ADDR | R/W | TRIM_REG1 | MBIT_TRIM | |
|---|------|-----|-----------|-----------|---|
| S | 0x1A | 0 | 0x03 | 0x0C | P |

| | ADDR | R/W | TRIM_REG2 | BIAS_TRIML | |
|---|------|-----|-----------|------------|---|
| S | 0x1A | 0 | 0x04 | 0x0C | P |

| | ADDR | R/W | TRIM_REG3 | BIAS_TRIMR | |
|---|------|-----|-----------|------------|---|
| S | 0x1A | 0 | 0x05 | 0x0C | P |

| | ADDR | R/W | TRIM_REG4 | CLK_TRIM | |
|---|------|-----|-----------|----------|---|
| S | 0x1A | 0 | 0x06 | 0x14 | P |

| | ADDR | R/W | TRIM_REG5 | BPA_TRIML | |
|---|------|-----|-----------|-----------|---|
| S | 0x1A | 0 | 0x07 | 0x0C | P |

| | ADDR | R/W | TRIM_REG6 | BPA_TRIMR | |
|---|------|-----|-----------|-----------|---|
| S | 0x1A | 0 | 0x08 | 0x0C | P |

| | ADDR | R/W | TRIM_REG7 | PU_TRIM | |
|---|------|-----|-----------|---------|---|
| S | 0x1A | 0 | 0x09 | 0x88 | P |

| | ADDR | R/W | CONFIG_REG | START / WAKEUP | |
|---|------|-----|------------|----------------|---|
| S | 0x1A | 0 | 0x01 | 0x09 | P |

| | ADDR | R/W | STATUS_REG | | ADDR | R/W | STATUS | |
|---|------|-----|------------|----|------|-----|--------|---|
| S | 0x1A | 0 | 0x02 | Sr | 0x1A | 1 | ?? | P |

WAIT 30ms

| | ADDR | R/W | STATUS_REG | | ADDR | R/W | STATUS | |
|---|------|-----|------------|----|------|-----|--------|---|
| S | 0x1A | 0 | 0x02 | Sr | 0x1A | 1 | ?? | P |

| | ADDR | R/W | READ_DATA1 | | ADDR | R/W | PTAT1 MSB | PTAT1 LSB | P0,0 MSB | P0,0 LSB | ... | Px,y MSB | Px,y LSB | |
|---|------|-----|------------|----|------|-----|-----------|-----------|----------|----------|-----|----------|----------|---|
| S | 0x1A | 0 | 0x0A | Sr | 0x1A | 1 | ?? | ?? | | | | | | P |

| | ADDR | R/W | READ_DATA2 | | ADDR | R/W | PTAT1 MSB | PTAT1 LSB | P0,0 MSB | P0,0 LSB | ... | Px,y MSB | Px,y LSB | |
|---|------|-----|------------|----|------|-----|-----------|-----------|----------|----------|-----|----------|----------|---|
| S | 0x1A | 0 | 0x0B | Sr | 0x1A | 1 | ?? | ?? | | | | | | P |

| | ADDR | R/W | CONFIG_REG | SLEEP | |
|---|------|-----|------------|-------|---|
| S | 0x1A | 0 | 0x01 | 0x00 | P |

12 Temperature Calculation

The object and ambient temperature can be calculated from the sensor output and the stored calibration data. The table below is showing an overview of the EEPROM.

| 16x16d | 0x00 | 0x01 | 0x02 | 0x03 | 0x04 | 0x05 | 0x06 | 0x07 | 0x08 | 0x09 | 0x0A | 0x0B | 0x0C | 0x0D | 0x0E | 0x0F |
|--------|---|------------|-----------------|-----------|-----------------------|---------------------|--------------|------|-----------|------------|-------------|-------------|--------------------|--------------------|---------------|------------|
| 0 | PixComp (float) | | PixComp (float) | | | | | | gradScale | GlobalGain | | | TN | epsilon | nrOfsePix/Max | DeadPixAdr |
| 10 | | | | | | | | | | | MBIT(calib) | BIAS(calib) | CLK(calib) | BPA(calib) | PU(calib) | |
| 20 | MBIT(user) | BIAS(user) | CLK(user) | BPA(user) | PU(user) | VddMeas(Th1) | VddMeas(Th2) | | | | | | PTAT (Th1) [unseq] | PTAT (Th2) [unseq] | | |
| 30 | | | | | PTAT-gradient (float) | PTAT-offset (float) | | | | | Device ID | | | | VddScGrad | VddScOff |
| 40 | VddCompGrad stored as 12 bit sigend values | | | | | | | | | | | | | | | |
| 90 | VddCompOff stored as 12 bit sigend values | | | | | | | | | | | | | | | |
| 100 | Th1 _i / Grad _i stored as 16 bit signed values | | | | | | | | | | | | | | | |
| 200 | Th2 _i / Offset _i stored as 16 bit signed values | | | | | | | | | | | | | | | |
| 300 | P _i stored as 16 bit unsigned values | | | | | | | | | | | | | | | |
| 3F0 | | | | | | | | | | | | | | | | |

All values are stored as unsigned 16 bit values in the little endian format unless they are specified otherwise. Grey marked areas are used during calibration or for future use and are Heimann Sensor reserved.

MBIT(calib), BIAS(calib), CLK(calib), BPA(calib) and PU(calib) are the settings for the registers that have been used during calibration. MBIT(user), BIAS(user), CLK(user), BPA(user) and PU(user) are free to be set by the user. The temperature calculation is only valid, if the same settings are used, that have been set during calibration!

TN is the table number and has to match the given table number in the sample code.

GlobalGain, VDDTh1, VDDTh2, PTATTh1 and PTATTh2 are stored as 16 bit unsigned values.

VDDTH1 and VDDTH2 is the used supply voltage during calibration measured by the sensor itself and stored in Digits.

The corresponding order of $ThGrad_{ij}$, $ThOffset_{ij}$ and P_{ij} to the Pixel number is given by the following overview:

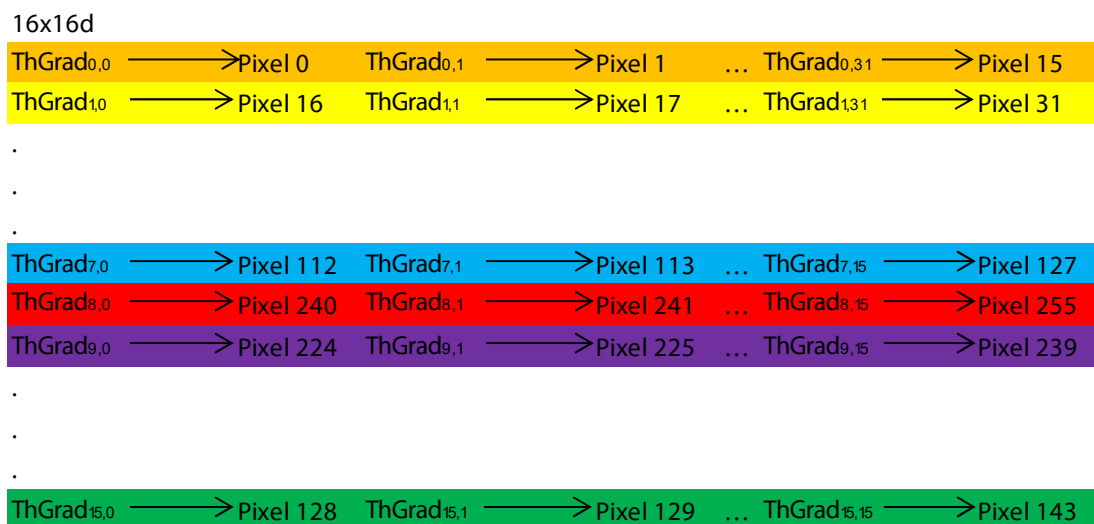


Figure 10: Readout Order 16x16d

The order of $VddCompGrad_{ij}$ and $VddCompOff_{ij}$ is similar to the electrical Offsets and have to be used block by block. $VddCompGrad_{ij}$ and $VddCompOff_{ij}$ are stored as 12 bit signed values with an offset of 0x800. Please check the sample code for a more detailed readout of the 12 bit values.



Figure 11: Readout of VDDCompGrad 16x16d

12.1 Ambient Temperature

The ambient temperature (T_a) is calculated from the average measured PTAT value, the $PTAT_{gradient}$ and the $PTAT_{offset}$. It is recommended to use a stack buffer for the PTAT values in order to get a more stable ambient temperature result.

$$T_a = PTAT_{av} \cdot PTAT_{gradient} + PTAT_{offset} \quad (\text{Value is given back in dK})$$

where:

| | |
|---|---|
| $PTAT_{gradient}$ | is the gradient of the PTAT stored in the EEPROM as a float value |
| $PTAT_{offset}$ | is the offset of the PTAT stored in the EEPROM as a float value |
| $PTAT_{av} = \frac{\sum_{i=0}^3 PTAT_i}{4}$ | is the average measured PTAT value |

12.2 Thermal Offset

The thermal offset of the sensor needs to be subtracted for each pixel to compensate for any thermal drifts.

$$V_{ij_Comp} = V_{ij} - \frac{ThGrad_{ij} \cdot Ta}{2gradScale} - ThOffset_{ij}$$

where:

| | |
|-----------------|--|
| ij | represents the row (i) and column (j) of the pixel |
| V_{ij_Comp} | is the thermal offset compensated voltage |
| V_{ij} | is the raw pixel data (digital), readout from the RAM |
| $ThGrad_{ij}$ | is the thermal gradient, stored in the EEPROM from 0x40 to 0x7F |
| $ThOffset_{ij}$ | is the thermal offset, stored in the EEPROM from 0x80 to 0xBF |
| $gradScale$ | is the scaling coefficient for the thermal gradient stored in the EEPROM |

12.3 Electrical Offset

The electrical offset is used to compensate changes in the supply voltage. This compensation is only a subtraction, so it can be done before or after the thermal offset compensation (here done afterwards). It is recommended

to use an electrical offset stack in order to get a more stable electrical offset result and a more stable temperature result at the end. The electrical offsets should be sampled every 8th to 10th frame.

The compensation for the top half is done by using the following formula:

$$V_{ij_Comp} * = V_{ij_Comp} - elOffset[(j + i \cdot 16) \% 64]$$

and the bottom half analogue with this formula:

$$V_{ij_Comp} * = V_{ij_Comp} - elOffset[(j + i \cdot 16) \% 64 + 64]$$

where:

| | |
|------------------|--|
| ij | represents the row (i) and column (j) of the pixel and electrical offset |
| $V_{ij_Comp} *$ | is the thermal and electrical offset compensated voltage |
| V_{ij_Comp} | is the thermal offset compensated voltage |
| $elOffset_{ij}$ | is the electrical offset belonging to Pixel ij |
| $i \% 64$ | is the rest of the integer division of i by 64 (e.g. 68%64=2) ("modulo") |

12.4 VDD Compensation

A supply voltage compensation called VddComp is used to take care of supply voltage changes. In order to use this compensation the supply voltage of the sensor (Vdd) has to be measured by the sensor from time to time by setting the configuration register and the average of Vdd 1 and Vdd 2 is resulting in Vdd (similar like $PTAT_{av}$). It is recommended to use a VDD stack buffer in order to get a more stable VDD value. The stack should be similar to the PTAT stack.

The compensation for the top half is done by using the following formula:

$$VDD_{av} = \frac{\sum_{i=0}^3 VDD_i}{4}$$

$$V_{ijVDDComp} = V_{ijComp} * \frac{\left(\frac{VddCompGrad[(j + i \cdot 16)\%64] \cdot PTAT_{av} + VddCompOff[(j + i \cdot 16)\%64]}{2^{VDDScGrad}} \right)}{2^{VDDScOff}}$$

$$\cdot \left(VDD_{av} - VDD_{TH1} - \left(\frac{VDD_{TH2} - VDD_{TH1}}{PTAT_{TH2} - PTAT_{TH1}} \right) \cdot (PTAT_{av} - PTAT_{TH1}) \right)$$

And the bottom half analogue with this formula:

$$V_{ijVDDComp} = V_{ijComp} * \frac{\left(\frac{VddCompGrad[(j + i \cdot 16)\%64 + 64] \cdot PTAT_{av} + VddCompOff[(j + i \cdot 16)\%64 + 64]}{2^{VDDScGrad}} \right)}{2^{VDDScOff}}$$

$$\cdot \left(VDD_{av} - VDD_{TH} - \left(\frac{VDD_{TH} - VDD_{TH}}{PTAT_{TH} - PTAT_{TH1}} \right) \cdot (PTAT_{av} - PTAT_{TH}) \right)$$

where:

| | |
|-------------------|--|
| ij | represents the row (i) and column (j) of the pixel |
| $V_{ij_VDDComp}$ | is the Vdd compensated voltage |
| $V_{ij_Comp} *$ | is the thermal and electrical offset compensated voltage |
| $VddComGrad[ij]$ | is the VddComp gradient belonging to Pixel ij |
| $VddComOff[ij]$ | is the VddComp offset belonging to Pixel ij |
| $i\%64$ | is the rest of the integer division of i by 64 (e.g. $66\%64=2$) ("modulo") |
| VDD_{av} | is the average measured supply voltage of the sensor in Digits |
| $VddScGrad$ | is a scaling coefficient and stored in the EEPROM 0x3E |
| $VddScOff$ | is a scaling coefficient and stored in the EEPROM 0x3F |
| VDD_{TH1} | is the supply voltage during calibration 1 stored in the EEPROM 0x25 |

| | |
|--------------|--|
| VDD_{TH2} | is the supply voltage during calibration 2 stored in the EEPROM 0x26 |
| $PTAT_{TH1}$ | is the PTAT value of calibration 1 stored in the EEPROM 0x2C |
| $PTAT_{TH2}$ | is the PTAT value of calibration 2 stored in the EEPROM 0x2D |

12.5 Object Temperature

The calculation of the object temperature is done by using a look-up table and doing a bi-linear interpolation, the matching table is given by the table number (TN). The table is supplied in a separate file named "Table.c". If you do not have the file, please ask Heimann Sensor for support.

The sensitivity coefficients ($PixC_{ij}$) are calculated in the following way:

$$PixC_{ij} = \left(\frac{P_{ij} \cdot (PixC_{max} - PixC_{min})}{65535} + PixC_{min} \right) \cdot \frac{\epsilon}{100} \cdot \frac{GlobalGain}{10000}$$

where:

| | |
|--------------|--|
| $PixC_{ij}$ | is the sensitivity coefficient for each pixel |
| P_{ij} | is the stored sensitivity coefficient scaled to 16 bit |
| $PixC_{min}$ | is the minimum sensitivity coefficient, used for scaling |
| $PixC_{max}$ | is the maximum sensitivity coefficient, used for scaling |
| ϵ | is the emissivity factor |
| $GlobalGain$ | is a factor for fine tuning of the sensitivity for all Pixel |

Leading to a compensation of the pixel voltage

$$V_{ij_PixC} = \frac{V_{ij_VDDComp} \cdot PCSCALEVAL}{PixC_{ij}}$$

where:

V_{ij_PixC} is the sensitivity compensated IR voltage

$PCSCALEVAL$ is a defined scaling coefficient, typically set to $1 \cdot 10^8$

13 Example Calculation

Example values:

$$PTAT_{av} = \frac{\sum_{i=0}^3 PTAT_i}{4} = 38152 \text{ Digits}$$

$$PTAT_{gradient} = 0.0211 \text{ dK/Digit}$$

$$PTAT_{offset} = 2195.0 \text{ dK}$$

$$V_{00} = 34435 \text{ Digits}$$

$$elOffset[0] = 34240$$

$$gradScale = 17$$

$$THGrad_{00} = 87 \rightarrow \text{signcheck } 87$$

$$THOffset_{00} = 65506 \rightarrow \text{signcheck } - 30$$

$$VDD_{av} = 35000$$

$$VDD_{TH1} = 33942$$

$$VDD_{TH2} = 36942$$

$$PTAT_{TH1} = 30000$$

$$PTAT_{TH2} = 42000$$

$$VddCompGrad[0] = 10356 \rightarrow \text{signcheck } 10356$$

$$VddCompOff[0] = 51390 \rightarrow \text{signcheck } - 14146$$

$$VddScGrad = 16$$

$$VddScOff = 23$$

$$PixC_{00} = 1 \cdot 10^8$$

$$PCSCALEVAL = 1 \cdot 10^8$$

Calculation of ambient temperature:

$$Ta = PTAT \cdot PTAT_{gradient} + PTAT_{offset} = 32357 \cdot 0.046 + 1511.6 \text{ dK} = 3000 \text{ dK}$$

Compensation of thermal offset:

$$V_{00_Comp} = V_{00} - \frac{ThGrad_{00} \cdot Ta}{2gradscale} - ThOffset_{00} = -\frac{-8842 \cdot 3000}{2^{15}} - 44 = 35200$$

Compensation of electrical offset:

$$V_{00_Comp}^* = V_{00_Comp} - elOffset_{00} = 35200 - 35000 = 200$$

13.1 Example Look-up Table

| Look-up table, TO values are given in dK | | | | |
|--|------|------|------|------|
| TA[dK]/dig | 2882 | 3032 | 3182 | 3332 |
| -64 | 1494 | 2128 | 2491 | 2775 |
| -32 | 2466 | 2692 | 2898 | 3091 |
| 0 | 2882 | 3032 | 3182 | 3332 |
| 32 | 3170 | 3285 | 3406 | 3530 |
| 64 | 3396 | 3491 | 3592 | 3699 |
| 96 | 3584 | 3665 | 3754 | 3848 |
| 128 | 3746 | 3818 | 3897 | 3981 |
| 160 | 3890 | 3954 | 4025 | 4102 |
| 192 | 4019 | 4078 | 4143 | 4214 |
| 224 | 4137 | 4191 | 4251 | 4317 |
| 256 | 4246 | 4296 | 4351 | 4413 |
| 288 | 4347 | 4393 | 4445 | 4503 |
| 320 | 4441 | 4485 | 4534 | 4588 |

$$V_{00_Comp} = \frac{200 \cdot 1 \cdot 10^8}{1.1 \cdot 10^8}$$

Ta was calculated before to 3000 dK.

The matching region in the look-up table is already marked yellow, the bi-linear interpolation is leading to an object temperature of 4026 dK = (4026dK-2732dK)/10 = 129.4 °C.

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The matching look-up table has to be taken from the "Table.c" file. Here is just shown an exemplary data for one optic.

| dig 1 Tab(dK) | 2782 | 2882 | 2982 | 3082 | 3182 | 3282 | 3382 |
|---------------|------|------|------|------|------|------|------|
| -512 | | | | | 1742 | 2002 | 2202 |
| -448 | | | | | 2094 | 2284 | 2442 |
| -384 | | | | | 2230 | 2420 | 2534 |
| -320 | | | | | 2534 | 2671 | 2797 |
| -256 | | | | | 2697 | 2822 | 2938 |
| -192 | 2287 | 2444 | 2587 | 2717 | 2839 | 2954 | 3065 |
| -128 | 2618 | 2812 | 2978 | 3125 | 3254 | 3375 | 3490 |
| -64 | 2842 | 2755 | 2865 | 2972 | 3078 | 3182 | 3285 |
| 0 | 2762 | 2882 | 2982 | 3082 | 3182 | 3282 | 3382 |
| 64 | 2908 | 2998 | 3089 | 3183 | 3278 | 3373 | 3473 |
| 128 | 3018 | 3101 | 3187 | 3276 | 3368 | 3462 | 3558 |
| 192 | 3121 | 3197 | 3278 | 3363 | 3452 | 3544 | 3638 |
| 256 | 3216 | 3286 | 3363 | 3445 | 3531 | 3621 | 3715 |
| 320 | 3305 | 3370 | 3443 | 3522 | 3606 | 3695 | 3787 |
| 384 | 3387 | 3449 | 3519 | 3595 | 3677 | 3764 | 3856 |
| 448 | 3465 | 3524 | 3590 | 3664 | 3745 | 3831 | 3922 |
| 512 | 3538 | 3595 | 3659 | 3731 | 3810 | 3895 | 3986 |
| 576 | 3609 | 3662 | 3724 | 3794 | 3872 | 3957 | 4047 |
| 640 | 3676 | 3727 | 3787 | 3855 | 3932 | 4016 | 4106 |
| 704 | 3740 | 3788 | 3847 | 3914 | 3990 | 4073 | 4163 |
| 768 | 3802 | 3849 | 3904 | 3971 | 4046 | 4128 | 4216 |
| 832 | 3861 | 3905 | 3960 | 4025 | 4100 | 4182 | 4271 |
| 896 | 3918 | 3960 | 4014 | 4078 | 4152 | 4233 | 4322 |
| 960 | 3973 | 4014 | 4066 | 4129 | 4202 | 4284 | 4372 |
| 1024 | 4026 | 4065 | 4117 | 4179 | 4251 | 4332 | 4421 |
| 1088 | 4077 | 4115 | 4166 | 4227 | 4299 | 4380 | 4469 |
| 1152 | 4127 | 4164 | 4213 | 4274 | 4345 | 4426 | 4515 |
| 1216 | 4175 | 4211 | 4260 | 4320 | 4391 | 4471 | 4560 |
| 1280 | 4222 | 4257 | 4306 | 4365 | 4435 | 4514 | 4603 |
| 1344 | 4268 | 4302 | 4350 | 4408 | 4478 | 4558 | 4647 |
| 1408 | 4312 | 4345 | 4391 | 4450 | 4520 | 4600 | 4689 |
| 1472 | 4355 | 4388 | 4433 | 4492 | 4561 | 4641 | 4730 |
| 1536 | 4396 | 4428 | 4474 | 4532 | 4601 | 4681 | 4770 |
| 1600 | 4436 | 4467 | 4514 | 4571 | 4640 | 4720 | 4809 |
| 1664 | 4474 | 4505 | 4553 | 4610 | 4679 | 4758 | 4848 |
| 1728 | 4510 | 4540 | 4588 | 4645 | 4714 | 4793 | 4882 |
| 1792 | 4545 | 4575 | 4623 | 4680 | 4749 | 4828 | 4917 |
| 1856 | 4579 | 4608 | 4656 | 4713 | 4782 | 4861 | 4950 |
| 1920 | 4612 | 4640 | 4688 | 4745 | 4814 | 4893 | 4982 |
| 1984 | 4645 | 4672 | 4720 | 4777 | 4846 | 4925 | 5014 |
| 2048 | 4676 | 4703 | 4751 | 4808 | 4877 | 4956 | 5045 |
| 2112 | 4706 | 4733 | 4781 | 4838 | 4907 | 4986 | 5075 |
| 2176 | 4735 | 4762 | 4810 | 4867 | 4936 | 5015 | 5104 |
| 2240 | 4763 | 4790 | 4838 | 4895 | 4964 | 5043 | 5132 |
| 2304 | 4790 | 4817 | 4865 | 4922 | 4991 | 5070 | 5159 |
| 2368 | 4817 | 4844 | 4892 | 4949 | 5018 | 5097 | 5186 |
| 2432 | 4843 | 4870 | 4918 | 4975 | 5044 | 5123 | 5212 |
| 2496 | 4869 | 4896 | 4944 | 5001 | 5070 | 5149 | 5238 |
| 2560 | 4894 | 4921 | 4969 | 5026 | 5095 | 5174 | 5263 |
| 2624 | 4919 | 4946 | 4994 | 5051 | 5120 | 5199 | 5288 |
| 2688 | 4943 | 4970 | 5018 | 5075 | 5144 | 5223 | 5308 |
| 2752 | 4967 | 4994 | 5042 | 5100 | 5169 | 5248 | 5333 |
| 2816 | 4990 | 5017 | 5065 | 5123 | 5192 | 5271 | 5358 |
| 2880 | 5013 | 5040 | 5088 | 5146 | 5215 | 5294 | 5383 |
| 2944 | 5035 | 5062 | 5110 | 5168 | 5237 | 5316 | 5401 |
| 3008 | 5057 | 5084 | 5132 | 5190 | 5259 | 5338 | 5423 |
| 3072 | 5078 | 5105 | 5153 | 5211 | 5280 | 5359 | 5445 |
| 3136 | 5099 | 5126 | 5174 | 5232 | 5301 | 5380 | 5467 |
| 3200 | 5119 | 5146 | 5194 | 5252 | 5321 | 5400 | 5489 |
| 3264 | 5138 | 5165 | 5213 | 5271 | 5340 | 5419 | 5511 |
| 3328 | 5157 | 5184 | 5232 | 5290 | 5359 | 5438 | 5523 |
| 3392 | 5175 | 5202 | 5250 | 5308 | 5377 | 5456 | 5545 |
| 3456 | 5193 | 5220 | 5268 | 5326 | 5395 | 5474 | 5567 |
| 3520 | 5210 | 5237 | 5285 | 5343 | 5412 | 5491 | 5589 |
| 3584 | 5227 | 5254 | 5302 | 5360 | 5429 | 5508 | 5606 |
| 3648 | 5243 | 5270 | 5318 | 5376 | 5445 | 5524 | 5628 |
| 3712 | 5259 | 5286 | 5334 | 5392 | 5461 | 5540 | 5650 |
| 3776 | 5274 | 5301 | 5349 | 5407 | 5476 | 5555 | 5672 |
| 3840 | 5289 | 5316 | 5364 | 5422 | 5491 | 5570 | 5694 |
| 3904 | 5303 | 5330 | 5378 | 5436 | 5505 | 5584 | 5716 |
| 3968 | 5317 | 5344 | 5392 | 5450 | 5519 | 5598 | 5738 |
| 4032 | 5330 | 5357 | 5405 | 5463 | 5532 | 5611 | 5760 |
| 4096 | 5343 | 5370 | 5418 | 5476 | 5545 | 5624 | 5782 |
| 4160 | 5355 | 5382 | 5430 | 5488 | 5557 | 5636 | 5804 |
| 4224 | 5367 | 5394 | 5442 | 5500 | 5569 | 5648 | 5826 |
| 4288 | 5379 | 5406 | 5454 | 5512 | 5581 | 5660 | 5848 |
| 4352 | 5390 | 5417 | 5465 | 5524 | 5593 | 5672 | 5870 |
| 4416 | 5401 | 5428 | 5476 | 5535 | 5604 | 5683 | 5892 |
| 4480 | 5412 | 5439 | 5487 | 5544 | 5613 | 5692 | 5914 |
| 4544 | 5422 | 5449 | 5497 | 5553 | 5622 | 5701 | 5936 |
| 4608 | 5432 | 5459 | 5507 | 5562 | 5631 | 5710 | 5958 |
| 4672 | 5441 | 5468 | 5516 | 5571 | 5640 | 5719 | 5980 |
| 4736 | 5450 | 5477 | 5525 | 5580 | 5649 | 5728 | 6002 |
| 4800 | 5459 | 5486 | 5534 | 5589 | 5658 | 5737 | 6024 |
| 4864 | 5467 | 5494 | 5542 | 5597 | 5666 | 5745 | 6046 |
| 4928 | 5475 | 5502 | 5550 | 5605 | 5675 | 5754 | 6068 |
| 4992 | 5483 | 5510 | 5558 | 5613 | 5683 | 5762 | 6090 |
| 5056 | 5490 | 5517 | 5565 | 5621 | 5691 | 5770 | 6112 |
| 5120 | 5497 | 5524 | 5573 | 5629 | 5699 | 5778 | 6134 |
| 5184 | 5504 | 5531 | 5581 | 5637 | 5707 | 5786 | 6156 |
| 5248 | 5510 | 5537 | 5587 | 5645 | 5715 | 5794 | 6178 |
| 5312 | 5516 | 5543 | 5593 | 5653 | 5723 | 5802 | 6200 |
| 5376 | 5521 | 5548 | 5598 | 5661 | 5731 | 5810 | 6222 |
| 5440 | 5526 | 5553 | 5603 | 5669 | 5739 | 5818 | 6244 |
| 5504 | 5531 | 5558 | 5608 | 5677 | 5747 | 5826 | 6266 |
| 5568 | 5535 | 5562 | 5612 | 5685 | 5755 | 5834 | 6288 |
| 5632 | 5539 | 5566 | 5617 | 5693 | 5763 | 5842 | 6310 |
| 5696 | 5543 | 5570 | 5620 | 5701 | 5771 | 5850 | 6332 |
| 5760 | 5546 | 5573 | 5625 | 5709 | 5779 | 5858 | 6354 |
| 5824 | 5549 | 5576 | 5630 | 5717 | 5787 | 5866 | 6376 |
| 5888 | 5552 | 5579 | 5635 | 5725 | 5795 | 5874 | 6398 |
| 5952 | 5554 | 5581 | 5640 | 5733 | 5803 | 5882 | 6420 |
| 6016 | 5556 | 5583 | 5645 | 5741 | 5811 | 5890 | 6442 |
| 6080 | 5558 | 5585 | 5650 | 5749 | 5819 | 5898 | 6464 |
| 6144 | 5560 | 5587 | 5655 | 5757 | 5827 | 5906 | 6486 |
| 6208 | 5561 | 5588 | 5660 | 5765 | 5835 | 5914 | 6508 |
| 6272 | 5562 | 5589 | 5665 | 5773 | 5843 | 5922 | 6530 |
| 6336 | 5563 | 5590 | 5670 | 5781 | 5851 | 5930 | 6552 |
| 6400 | 5564 | 5591 | 5675 | 5789 | 5859 | 5938 | 6574 |
| 6464 | 5564 | 5591 | 5680 | 5797 | 5867 | 5946 | 6596 |
| 6528 | 5564 | 5591 | 5685 | 5805 | 5875 | 5954 | 6618 |
| 6592 | 5564 | 5591 | 5690 | 5813 | 5883 | 5962 | 6640 |
| 6656 | 5564 | 5591 | 5695 | 5821 | 5891 | 5970 | 6662 |
| 6720 | 5564 | 5591 | 5700 | 5829 | 5899 | 5978 | 6684 |
| 6784 | 5564 | 5591 | 5705 | 5837 | 5907 | 5986 | 6706 |

| | | | | | | | |
|------|------|------|------|------|------|------|------|
| 6848 | 5421 | 6431 | 5462 | 6514 | 6584 | 6673 | 6777 |
| 6912 | 6437 | 6447 | 6478 | 6530 | 6600 | 6689 | 6794 |
| 6976 | 6453 | 6463 | 6494 | 6546 | 6616 | 6705 | 6810 |
| 7040 | 6468 | 6479 | 6510 | 6562 | 6632 | 6721 | 6826 |
| 7104 | 6485 | 6495 | 6526 | 6577 | 6646 | 6735 | 6840 |
| 7168 | 6501 | 6511 | 6542 | 6593 | 6664 | 6753 | 6858 |
| 7232 | 6517 | 6526 | 6557 | 6609 | 6680 | 6769 | 6874 |
| 7296 | 6532 | 6542 | 6573 | 6624 | 6695 | 6784 | 6889 |
| 7360 | 6548 | 6557 | 6588 | 6640 | 6711 | 6800 | 6906 |
| 7424 | 6563 | 6572 | 6603 | 6655 | 6726 | 6815 | 6922 |
| 7488 | 6578 | 6588 | 6619 | 6670 | 6741 | 6830 | 6937 |
| 7552 | 6593 | 6603 | 6634 | 6685 | 6756 | 6845 | 6953 |
| 7616 | 6609 | 6618 | 6649 | 6700 | 6771 | 6860 | 6969 |
| 7680 | 6624 | 6633 | 6664 | 6715 | 6786 | 6875 | 6984 |
| 7744 | 6639 | 6648 | 6679 | 6730 | 6801 | 6890 | 6999 |
| 7808 | 6654 | 6663 | 6694 | 6745 | 6816 | 6905 | 7014 |
| 7872 | 6669 | 6677 | 6708 | 6760 | 6831 | 6920 | 7029 |
| 7936 | 6683 | 6692 | 6723 | 6774 | 6845 | 6934 | 7044 |
| 8000 | 6698 | 6707 | 6737 | 6789 | 6860 | 6949 | 7059 |
| 8064 | 6712 | 6721 | 6752 | 6803 | 6874 | 6963 | 7074 |
| 8128 | 6727 | 6735 | 6766 | 6817 | 6888 | 6977 | 7089 |
| 8192 | 6741 | 6750 | 6781 | 6832 | 6903 | 6992 | 7104 |
| 8256 | 6756 | 6764 | 6795 | 6846 | 6917 | 7006 | 7119 |
| 8320 | 6770 | 6778 | 6809 | 6860 | 6931 | 7020 | 7133 |
| 8384 | 6784 | 6792 | 6823 | 6874 | 6945 | 7034 | 7147 |
| 8448 | 6798 | 6806 | 6837 | 6888 | 6959 | 7048 | 7161 |
| 8512 | 6812 | 6820 | 6851 | 6902 | 6973 | 7062 | 7175 |
| 8576 | 6826 | 6834 | 6865 | 6916 | 6987 | 7076 | 7189 |
| 8640 | 6840 | 6848 | 6879 | 6930 | 7001 | 7090 | 7205 |
| 8704 | 6854 | 6862 | 6893 | 6944 | 7015 | 7104 | 7219 |
| 8768 | 6868 | 6876 | 6907 | 6958 | 7029 | 7118 | 7233 |
| 8832 | 6881 | 6889 | 6920 | 6971 | 7042 | 7131 | 7247 |
| 8896 | 6895 | 6903 | 6934 | 6985 | 7056 | 7145 | 7261 |
| 8960 | 6909 | 6917 | 6948 | 7000 | 7071 | 7160 | 7275 |
| 9024 | 6922 | 6930 | 6961 | 7012 | 7083 | 7172 | 7289 |
| 9088 | 6935 | 6943 | 6974 | 7024 | 7095 | 7184 | 7303 |
| 9152 | 6949 | 6957 | 6988 | 7039 | 7110 | 7199 | 7317 |
| 9216 | 6962 | 6970 | 7001 | 7052 | 7123 | 7212 | 7331 |
| 9280 | 6975 | 6983 | 7014 | 7065 | 7136 | 7225 | 7345 |
| 9344 | 6988 | 6996 | 7027 | 7078 | 7149 | 7238 | 7359 |
| 9408 | 7001 | 7009 | 7040 | 7091 | 7162 | 7251 | 7373 |
| 9472 | 7015 | 7022 | 7053 | 7104 | 7175 | 726 | |

13.2 Pixel Masking

A maximum of 1 defect Pixel is allowed on the complete array, this means that at least 99.5 % of the Pixels are working correctly. The amount of defect Pixels is given in the EEPROM at address 0x0E (LSB) and is named *NrOfDefPix*. *DeadPixAdr* (EEPROM 0x0F) is the address of the defect Pixel and *DeadPixMask* (EEPROM 0x0E, MSB) determines the neighbours, that should be used for masking the pixel. A simple averaging of all selected nearest neighbours is done to overwrite the temperature value of these Pixel.

The values for *NrOfDefPix* and *DeadPixMask* are stored as 8 bit unsigned values, the *DeadPixAdr* is saved as an 16 bit unsigned value.

The order of the top and bottom half is the same as the readout order that is stated in Serial Order of Frame.

The value stored in *DeadPixAdr* is equal to the pixel number if *DeadPixAdr* is <0x80. If the value is greater, that means between 0d128 and 0d255, the actual read-out pixel has to be calculated first. For example: If you have a pixel number of 199 stored to the EEPROM, this is actually 183. The pixel number, that is store in the EEPROM corresponds to the number of the read-out pixel. So the bottom half is mirrored.

Example calculation:

$$adaptedAdr[i] = 256 + 128 - DeadPixAdr[i] + k[i] \cdot 2 - 16$$

where:

adaptedAdr[i] is the adapted dead pixel address

k[i] is the column of the corresponsive pixel (for pixel number 199 this would be 7)

$$adaptedAdr[i] = 256 + 128 - 199 + 14 - 16 = 183$$

The neighbours to use is given in a binary format and the order is shown in the overview below in decimal and binary values for the top and bottom half.

top half

| | | |
|-----|---------|---|
| 128 | 1 | 2 |
| 64 | DeadPix | 4 |
| 32 | 16 | 8 |

| | | |
|-------------|-------------|-------------|
| 0b1000 0000 | 0b0000 0001 | 0b0000 0010 |
| 0b0100 0000 | DeadPix | 0b0000 0100 |
| 0b0010 0000 | 0b0001 0000 | 0b0000 1000 |

bottom half

| | | |
|-----|---------|---|
| 32 | 16 | 8 |
| 64 | DeadPix | 4 |
| 128 | 1 | 2 |

| | | |
|-------------|-------------|-------------|
| 0b0010 0000 | 0b0001 0000 | 0b0000 1000 |
| 0b0100 0000 | DeadPix | 0b0000 0100 |
| 0b1000 0000 | 0b0000 0001 | 0b0000 0010 |

Example 1 for the masking:

$NrOfDefPix = 0x01$
 $DeadPixAdr[0] = 0x000A \rightarrow$ Pixel 10
 $DeadPixMask[0] = 0x7C \rightarrow 0b0111\ 1100$ (top)

The readout order is the same as shown in Serial Order of Frames, Figure 4.

According to the sample values 1 Pixel is defect and need to be interpolated. The Pixels is on the top half. Assuming that the neighbouring Pixels are having the temperature data stated below and the green marked cells are used for averaging (according to DeadPixMask), then the interpolated temperature will be the following:

$$\text{Pixel 10} = \frac{3007 + 3008 + 3008 + 3011 + 3009}{5} dK = \frac{15043}{5} dK \approx 3009dK$$

All values are given in dK

| | | |
|------|----------|------|
| | | |
| 3007 | Pixel 10 | 3008 |
| 3008 | 3011 | 3009 |

| | | |
|----------|----------|----------|
| | | |
| Pixel 9 | Pixel 10 | Pixel 11 |
| Pixel 25 | Pixel 26 | Pixel 27 |

Example 2 for the masking:

$NrOfDefPix = 0x01$
 $DeadPixAdr[0] = 0x00C7 \rightarrow$ Pixel 199 (read-out pixel) actual pixel number is 183
 $DeadPixMask[0] = 0xFE \rightarrow 0b1111\ 1110$ (bot)

$$\text{Pixel 183} = \frac{3010 + 3012 + 3005 + 3007 + 3008 + 3008 + 3009}{7} dK = \frac{21059}{7} dK \approx 3008dK$$

| | | |
|------|-----------|------|
| 3010 | 3012 | 3005 |
| 3007 | Pixel 183 | 3008 |
| 3008 | 3011 | 3009 |

| | | |
|-----------|-----------|-----------|
| Pixel 166 | Pixel 167 | Pixel 168 |
| Pixel 182 | Pixel 183 | Pixel 184 |
| Pixel 198 | Pixel 199 | Pixel 200 |

14 Order Code Chart

| | | | | | | |
|------------|----|-----------------|------|-----|----------|--------------|
| HTPA16x16d | R3 | L1.0/0.8 | F5.0 | UHi | A | (USB) |
| HTPA16x16d | R3 | L1.0/0.8 | F5.0 | UHi | A | (UDP) |
| HTPA16x16d | R3 | L1.0/0.8 | F5.0 | UHi | M | (UDP) |
| HTPA16x16d | R3 | L1.0/0.8 | F5.0 | UHi | C | |
| HTPA16x16d | R3 | L1.6/0.8 | F5.0 | UHi | A | (USB) |
| HTPA16x16d | R3 | L1.6/0.8 | F5.0 | UHi | A | (UDP) |
| HTPA16x16d | R3 | L1.6/0.8 | F5.0 | UHi | M | (UDP) |
| HTPA16x16d | R3 | L1.6/0.8 | F5.0 | UHi | C | |
| HTPA16x16d | R3 | L2.1/0.8 | F5.0 | UHi | A | (USB) |
| HTPA16x16d | R3 | L2.1/0.8 | F5.0 | UHi | A | (UDP) |
| HTPA16x16d | R3 | L2.1/0.8 | F5.0 | UHi | M | (UDP) |
| HTPA16x16d | R3 | L2.1/0.8 | F5.0 | UHi | C | |
| HTPA16x16d | R3 | L5.0/1.0 | F7.7 | UHi | A | (USB) |
| HTPA16x16d | R3 | L5.0/1.0 | F7.7 | UHi | A | (UDP) |
| HTPA16x16d | R3 | L5.0/1.0 | F7.7 | UHi | M | (UDP) |
| HTPA16x16d | R3 | L5.0/1.0 | F7.7 | UHi | C | |

Bold: Selectable options

Regular: Fixed/Not selectable

15 Outer Dimension

